

1. Fundamental and derivate quantities and units

- Fundamental Physical quantities are those that can be directly defined, and for which the units are chosen arbitrarily, independent of others physical quantities.

No.	Fundamental Quantity	Unit	Symbol	Dimension
1	Length	Meter	m	L
2	Time	Second	s	T
3	Mass	Kilogram	kg	M
4	Current intensity	Ampere	A	I
5	Light intensity	Candela	Cd	J
6	Temperature	Kelvin	K	θ
7	Solid angle	Ste-radian	Sr	
8	Plane angle	Radian	rad	

- The derivative physical quantities are those that are defined indirectly. They have the measurement units' functions of fundamental units.

If we have:

- $U = U(L, T, M, I, J, \theta)$
- $[U] = L^{\alpha} T^{\beta} M^{\gamma} I^{\delta} J^{\epsilon} \theta^{\xi}$

2 The homogeneity of physical equations:

- The physical formulas are invariant to the measurement units' transformation.

3 Examples:

3.1 Velocity:

$$v = \lim_{\Delta t \rightarrow 0} \frac{\Delta x}{\Delta t} = \frac{dx}{dt} \quad [v] = \frac{[x]}{[t]} = \frac{m}{s} = m \cdot s^{-1} = L \cdot T^{-1} \quad (1)$$

3.2 Acceleration:

$$a = \lim_{\Delta t \rightarrow 0} \frac{\Delta v}{\Delta t} = \frac{dv}{dt} \quad [a] = \frac{[v]}{[t]} = \frac{m}{s^2} = m \cdot s^{-2} = L \cdot T^{-2} \quad (2)$$

3.3 Impulse:

$$p = m \cdot v \quad [p] = [m] \cdot [v] = kg \frac{m}{s} = kg \cdot m \cdot s^{-1} = M \cdot L \cdot T^{-1} \quad (3)$$

3.4 Force:

$$F = \lim_{\Delta t \rightarrow 0} \frac{\Delta p}{\Delta t} = \frac{dp}{dt} = \frac{dmv}{dt} = m \frac{dv}{dt} = m \cdot a$$

$$[F] = \frac{[p]}{[t]} = \frac{\text{kg} \cdot \text{m}}{\text{s}^2} = \text{kg} \cdot \text{m} \cdot \text{s}^{-2} = \text{M} \cdot \text{L} \cdot \text{T}^{-2} \quad [F] = 1 \frac{\text{kg} \cdot \text{m}}{\text{s}^2} = 1\text{N} \quad (4)$$

3.5 Pressure:

$$P = \frac{dF}{dS} \quad [P] = \frac{[F]}{[S]} = \frac{\text{kg}}{\text{s}^2 \cdot \text{m}} = \text{kg} \cdot \text{m}^{-1} \cdot \text{s}^{-2} = \text{M} \cdot \text{L}^{-1} \cdot \text{T}^{-2} \quad [P] = 1 \frac{\text{N}}{\text{m}^2} = 1\text{Pa} \quad (5)$$

3.6 Mechanical work:

$$dL = F \cdot ds \quad [L] = [F] \cdot [s] = \text{kg} \frac{\text{m}^2}{\text{s}^2} = \text{kg} \cdot \text{m}^2 \cdot \text{s}^{-2} = \text{M} \cdot \text{L}^2 \cdot \text{T}^{-2} \quad [L] = 1\text{N} \cdot \text{m} = 1\text{J} \quad (6)$$

3.7 Kinetic energy:

$$E_c = \frac{m \cdot v^2}{2};$$

$$[E_c] = [m][v]^2 = \frac{\text{kg} \cdot \text{m}^2}{\text{s}^2} = \text{kg} \cdot \text{m}^2 \cdot \text{s}^{-2} = \text{M} \cdot \text{L}^2 \cdot \text{T}^{-2}; \quad [E_c] = 1\text{kg} \cdot \text{m}^2 \cdot \text{s}^{-2} = 1\text{J} \quad (7)$$

3.8 Gravitational potential Energy:

$$E_p = m \cdot g \cdot h$$

$$[E_p] = [m] \cdot [g] \cdot [h] = \text{kg} \frac{\text{m}^2}{\text{s}^2} = \text{kg} \cdot \text{m}^2 \cdot \text{s}^{-2} = \text{M} \cdot \text{L}^2 \cdot \text{T}^{-2}; \quad [E_p] = 1\text{kg} \cdot \text{m}^2 \cdot \text{s}^{-2} = 1\text{J} \quad (8)$$

3.9 Elastically potential Energy:

$$E_{p,e} = \frac{k \cdot x^2}{2}$$

$$[E_{p,e}] = [k][x]^2 = \frac{\text{kg} \cdot \text{m}^2}{\text{s}^2} = \text{kg} \cdot \text{m}^2 \cdot \text{s}^{-2} = \text{M} \cdot \text{L}^2 \cdot \text{T}^{-2}; \quad [E_{p,e}] = 1\text{kg} \cdot \text{m}^2 \cdot \text{s}^{-2} = 1\text{J} \quad (9)$$

3.10 Power:

$$P = \frac{dE}{dt}$$

$$[P] = \frac{[E]}{[t]} = \frac{\text{kg} \cdot \text{m}^2}{\text{s}^3} = \text{kg} \cdot \text{m}^2 \cdot \text{s}^{-3} = \text{M} \cdot \text{L}^2 \cdot \text{T}^{-3} \quad [P] = 1 \frac{\text{J}}{\text{s}} = 1\text{W} \quad (10)$$

3.11 Density:

$$\rho = \frac{dm}{dV} \quad [\rho] = \frac{[m]}{[V]} = \frac{\text{kg}}{\text{m}^3} = \text{kg} \cdot \text{m}^{-3} = \text{M} \cdot \text{L}^{-3} \quad (11)$$

3.12 Angular velocity:

$$\omega = \frac{d\varphi}{dt} \qquad [\omega] = \frac{[\varphi]}{[t]} = \frac{\text{rad}}{\text{s}} = \text{rad} \cdot \text{s}^{-1} = \text{T}^{-1} \qquad (12)$$

3.13 Solid angle:

$$d\Omega = \frac{dA}{R^2} \qquad [\Omega] = \frac{[A]}{[R]^2} = \frac{\text{m}^2}{\text{m}^2} = \text{L}^0 = 1 \qquad [\Omega] = 1\text{L}^0 = 1\text{steradian} \qquad (13)$$

- 4 Establishes into a constant approximation the formula of a gravitational (mathematical) pendulum, T using the homogeneity of the dimensional equations.
- 5 The mass of a parachute with jumper (parachutist) is $m = 100$ kg, and is launched from a tower completely open with no initial velocity. Find the velocity expression, $v(t)$ and the velocity limit if we know that the resistance force is proportional with the velocity, $R = kv$, where $k = 500$ Ns/m.
6. A skier with the weight G descends a hill that make an angle α with the horizontal plane. The motion equations are $x = Agt^2$ along the hill and $y = 0$, where g is the gravitational acceleration and A a constant coefficient. How much is the friction force between skier and snow on the hill. (Particular case: the skier mass $m = 70$ kg, angle $\alpha = 30^\circ$; $A = 0.1$).
7. A material point with mass m is moving along a trajectory given by the Cartesian components: $x(t) = A \cos(kt)$ and $y(t) = B \cos(kt)$. Characterize the force F that produces this type of motion if we know that the force depends only by the material point position. Give some examples.
8. On a body with a mass $m = 2$ kg are acting two forces, $F_1 = 3$ N and $F_2 = 4$ N, which are characterized by the angles $\alpha_1 = 60^\circ$, and $\alpha_2 = 120^\circ$ respectively, with the direction of velocity \vec{v}_0 . Find the body acceleration, \mathbf{a} , velocity, \mathbf{v} and the distance covered into a time $t = 10$ s starting from the beginning of motion (Particular case $v_0 = 20$ m/s).
9. A tractor is traveling with a velocity of $v_0 = 36$ km/h. If the radius of the wheel is $R = 0.5$ m find out:
 - a) The parametric motion equations of a point from the external wheel circumference.

- b) The tangential velocity components and the value of velocity.
- c) The path distance by a point between two contacts with the road.
10. A body with a mass $m = 5$ kg can slide with friction on a horizontal surface if is pushed by a spiral spring, with an elastic constant $k = 200$ N/m, and which was compressed at half of his length $l = 20$ cm. Find out:
- a) the mechanical work of friction force during expansion.
- b) how much must is the friction coefficient if in the final position the spring in not stressed.
11. A concrete cube with the side of $a = 0.8$ m and a density of 2500kg/m^3 must be tipped around an edge. Calculate:
- a) Point of application direction and value of the minimal force needed to turn turn-over;
- b) The expression of a horizontal force that can turn-over the concrete block if this is applied on superior edge as function of rotation angle.
- c) The mechanical work spent for turning over the concrete block.
12. On an inclined plane with inclination $\alpha = \arcsin(3/5)$ and length $l = 2.1$ m is rolling with no sliding friction an homogeneous sphere of mass $m = 40$ g and radius $R = 10$ mm. How much is the transversal velocity, angular velocity and frequency at the base of the plane.
13. Demonstrate that after a perfect elastic collision of two hokey pucks of the same mass initial one being at rest the angle between the directions of pucks is 90^0 . How much are the velocities and scatter angle θ_2 if the initial velocity of projectile puck is $v = 40$ km/h and $\theta_1 = 60^0$?